Decide-and-Forward Short-Packet Relaying in the Internet of Things: Timely Status Updates

Dongsheng Zheng, Yuli Yang, Senior Member, IEEE, Lai Wei, and Bingli Jiao, Senior Member, IEEE

Abstract—In this paper, a decode-and-forward (DF) short-packet relaying model is developed to achieve timely status updates for intelligent monitoring within the Internet of Things (IoT), where the status updates generated at an IoT device are delivered to a remote server with the aid of a relay in both half-duplex (HD) and full-duplex (FD) modes. To characterise the data freshness of status updates, we exploit the age of information (AoI) as a metric, which is defined as the time elapsed since the generation of the latest successfully decoded status update. The average AoI is formulated and minimised for both HD-DF and FD-DF relaying IoT networks in finite blocklength regime. For the HD-DF relaying, we introduce a perfect approximation of the average AoI to solve the problem of average AoI minimisation with the optimal blocklengths in two phases. For the FD-DF relaying, we propose an iterative algorithm to solve the problem of average AoI minimisation by optimising the relay’s transmit power and the blocklength. Illustrative numerical results not only substantiate the validity of our proposed algorithms, but also provide useful references for the IoT monitoring network design, specifically for the transmit power thresholds at the IoT device and the relay.

Index Terms—Age of information (AoI), decode-and-forward (DF), finite blocklength regime, full duplex (FD), half duplex (HD), short-packet relaying, status updates.

I. INTRODUCTION

The Internet of Things (IoT) is a promising paradigm to carry out ubiquitous connectivity of massive devices and implement a wide range of advanced applications in agriculture, industry, medicine, and allied sectors [1], [2]. As the monitoring infrastructure creates a foundation for IoT services, e.g., smart home, smart healthcare, intelligent transportation, industrial automation, etc., various types of sensors and actuators are deployed in IoT monitoring networks to collect and deliver the status updates of specific physical parameters such as temperature, humidity, wind strength, and so on [3], [4].

To provide accurate and effective services, an IoT monitoring network has to maintain the data freshness of status updates for the monitored physical parameters [5], [6]. The age of information (AoI) was proposed in the seminal works [7] and [8] as a new metric to measure the data freshness in a network. The way to improve the data freshness is to minimise the AoI. Different from the metric to measure transmission delay, the concept of AoI characterises the timestamp of the latest successfully decoded status update at the destination. The state-of-the-art, the challenges and the future directions in the research of this fundamentally novel metric have been thoroughly surveyed in [9] and [10].

As a key measurement of transmission efficiency, the average AoI is used to evaluate the data freshness of status updates in a network from an ergodic perspective, which has been widely studied. The average AoI of G/G/1/1 systems was investigated in [11], with the service protocols concerning blocking and preemption. The average version age at each node in a network was evaluated in [12], where the status updates were delivered through a memoryless gossip protocol. The average AoI and average peak AoI of edge computing systems were analysed in [13], where sensor nodes firstly process the acquired information and then transmit the processed results to an edge receiver. The average AoI in energy harvesting wireless sensor networks was investigated in [14]–[16]. Under the constraints of average AoI and power consumption, the long-term average throughput was analysed and maximised in [17] given both perfect channel state information at the transmitter (CSIT) and statistical CSIT. Moreover, the impacts of quantization [18], source coding [19], channel coding [20], partial update [21], and selective encoding [22] on the AoI in various systems have been considered. Besides, a new performance metric for status updates, referred to as the age of incorrect information was developed in [23], to better capture the wrong information’s deteriorating effect from the timeline-and error-based perspective.

In practice, short-packet protocols have been exploited for the status updates in IoT networks to achieve ultra-reliable and low-latency communications [24], [25]. Recent information-theoretic advances in the analysis in finite blocklength regime have established a basis for the design of short-packet communications [26]. Unlike the theoretical framework in infinite blocklength regime grounded upon Shannon’s convergence of optimal coding rate to the error-free channel capacity, short-packet communications have to inevitably suffer from decoding error in the finite blocklength regime. Given a packet error probability, tight bounds on maximal coding rate of short-packet communications have been derived in [27]. Based on these works, the AoI performance of short-packet communications have been studied in finite blocklength regime. For example, the average AoI of short-packet communications was investigated in [28] with various packet management schemes, including non-preemption scheme, preemption scheme, and retransmission scheme. In [29], the average AoI of status updates...
was analysed and compared in finite blocklength regime for time-division and frequency-division multiple access systems. In [30], the average AoI of machine-type communications with short packets was developed and optimised, where the packet error probabilities were compared for the strategies of discarding and retransmitting the packets decoded unsuccessfully.

Furthermore, network densification is an influential approach to address the challenges of exponentially increasing data services and massive connectivity in the IoT [31]. The access point within a small cell takes on the role of a relay to forward the IoT devices’ status updates to the remote server [32], [33]. Within macro cells, due to the transmit power limitations on IoT devices, their communications with the remote server also need to be implemented through the aid of a relay. Buyukates et al. investigated the average AoI of multihop multicast networks in [34], and Li et al. analysed the weighted average AoI of amplify-and-forward (AF) two-way relaying systems in [35].

As a common and dynamic topology in IoT wireless networks, the decode-and-forward (DF) relaying achieves better performance than the AF [36]–[38]. To the best of our knowledge, theoretical principles governing DF short-packet relaying IoT networks have not yet been addressed to assess their performance in maintaining the data freshness of status updates. Motivated by this, herein we study the AoI performance of DF short-packet relaying in finite blocklength regime, where the analytic expressions of average AoI are obtained for both half-duplex (HD) and full-duplex (FD) DF relaying IoT networks. Furthermore, we propose efficient algorithms to solve the optimisation problems for the average AoI minimisation through optimal designs of blocklength and transmit power.

The novelty of our work is compared with related studies of the AoI concept in Table I. In particular, our main contributions in this paper are three-fold:

- The HD-DF and FD-DF relaying models are developed to quantify the data freshness of status updates in the metric of AoI for the DF short-packet relaying IoT networks.
- The average AoI in finite blocklength regime is formulated for the HD-DF and FD-DF relaying IoT networks, with analytic expressions achieved.
- Efficient algorithms are proposed to solve the optimisation problems of the average AoI minimisation in HD-DF and FD-DF relaying IoT networks, with the optimal designs of blocklength and transmit power.

To detail the above highlighted contributions, the remainder of this paper is organized as follows. In Section II, the system models of HD-DF and FD-DF relaying IoT networks are presented, followed by the introductions to the analysis in finite blocklength regime and the concept of AoI. Subsequently, Sections III and IV formulate and minimise the average AoI in finite blocklength regime for the HD-DF and FD-DF relaying IoT networks, respectively. Illustrative numerical results are provided in Section V to substantiate our theoretical formulations and proposed algorithms for the average AoI minimisation. Finally, this paper is concluded in Section VI.

**Notations:** $f_X(x)$ and $F_X(x)$ stand for the probability density function (pdf) and the cumulative distribution function (cdf) of a random variable $X$, respectively. Moreover, $Q(x) = \int_x^\infty (1/\sqrt{2\pi}) \exp(-t^2/2)dt$ is the Q-function, and $\mathbb{E}()$ denotes the expectation (mean) operator. The greatest integer function and the least integer function are denoted by $\lfloor \cdot \rfloor$ and $\lceil \cdot \rceil$, respectively.

**II. SYSTEM MODEL AND PRELIMINARIES**

In this section, the system models of HD-DF and FD-DF relaying networks are firstly presented. Then, the analysis of short-packet communications in finite blocklength regime and the definition of AoI are introduced.

**A. Decode-and-Forward Relaying**

Consider a DF relaying network shown in Fig. 1, where the status updates generated at an IoT device are delivered to a remote server with the aid of a relay. To achieve reliable transmissions of status updates over wireless channels, the automatic repeat request (ARQ) mechanism is adopted. Besides, both HD and FD modes are applied in the DF relaying.

1) **HD-DF Relaying:** In this mode, the transmission of each status update is composed of two phases, as shown in Fig. 1(a). In Phase 1, the IoT device transmits current status update to the relay. Once the relay successfully decodes the status update, it will send an acknowledgement (ACK) to the IoT device. If the IoT device does not receive an ACK before the predetermined timeout, it will retransmit this status update until receiving an ACK. In Phase 2, the relay transmits its decoded status update to the remote server whilst the IoT device keeps silent. Once the remote server successfully decodes the status update, an

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<th>Contributions</th>
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ACK is fed back to the relay and the IoT device, which triggers the IoT device to commence with the transmission of next status update. Otherwise, the relay will retransmit its currently decoded status update to the remote server until receiving an ACK.

2) FD-DF Relaying: In this mode, the relay receives the status update sent from the IoT device and, concurrently, transmits its decoded status update to the remote server, through the same time/frequency resource. In the link between the IoT device and the relay, an ACK fed back to the IoT device on the relay’s successful decoding will trigger the IoT device’s transmission of next status update. In the link between the relay and the remote server, the relay will be allowed to commence with the transmission of its next decoded status update once receiving an ACK from the remote server. However, the relay is likely to be ready for the transmission of its next decoded status update before receiving an ACK from the remote server. In this case, based on the preemption [28], the relay will replace its currently decoded status update with the succeeding one, even if the current one has not yet been successfully decoded by the remote server.

B. Short-Packet Communications

We investigate the DF relaying with short-packet communications in the finite blocklength regime, where the coding rate is denoted by \( R = D/n \), with \( D \) and \( n \) standing for the number of information bits pertaining to a status update and the blocklength, respectively. Note that, \( D \) is the same for both HD and FD modes, i.e., both modes use the same amount of information bits to characterise each status update.

A tight bound on the coding rate is given by [27]

\[
R = \log_2(1 + \gamma) - \sqrt{\frac{V}{n}} \frac{Q^{-1}(\varepsilon)}{\ln 2},
\]

where \( \gamma \) and \( \varepsilon \) denote the signal-to-noise power ratio (SNR) and the packet error probability, respectively. Moreover, \( V = 1 - (1 + \gamma)^{-2} \) is the channel dispersion, and \( Q^{-1}(\cdot) \) is the inverse function of \( Q(x) \).

From (1), the packet error probability \( \varepsilon \) is formulated as

\[
\varepsilon = Q\left( \frac{(\ln 2)\sqrt{n}(\log_2(1 + \gamma) - D/n)}{\sqrt{1 - (1 + \gamma)^{-2}}} \right) \approx Q(\theta(D, n, \gamma)),
\]

where the notation

\[
\theta(D, n, \gamma) = \frac{(\ln 2)\sqrt{n}(\log_2(1 + \gamma) - D/n)}{\sqrt{1 - (1 + \gamma)^{-2}}}
\]

is used for the simplicity of expression.

In a general block-fading channel, the average packet error probability is calculated using

\[
\mathbb{E}(\varepsilon) = \int_0^\infty Q(\theta(D, n, x)) f_\gamma(x) dx,
\]

where \( f_\gamma(x) \) is the pdf of the SNR \( \gamma \).

To gain the closed-form expression of \( \mathbb{E}(\varepsilon) \), a linear approximation of the Q-function is given by [39], [40]

\[
Q(\theta(D, n, x)) \approx \begin{cases} 
1, & x \leq \alpha - \frac{1}{2\beta}, \\
\frac{1}{2} - \beta(x - \alpha), & \alpha - \frac{1}{2\beta} \leq x \leq \alpha + \frac{1}{2\beta}, \\
0, & x \geq \alpha + \frac{1}{2\beta},
\end{cases}
\]

where \( \alpha = 2^{D/n} - 1 \) and \( \beta = \sqrt{n/[2\pi(2^{2D/n} - 1)]} \). To further validate the effectiveness of (4), we plot \( Q(\theta(D, n, x)) \) and its linear approximation in Fig. 2.

Substituting (4) into (3), we rewrite the average packet error probability as

\[
\mathbb{E}(\varepsilon) = \beta \int_{\alpha - 1/(2\beta)}^{\alpha + 1/(2\beta)} F_\gamma(x) dx,
\]

where \( F_\gamma(x) \) is the cdf of the SNR \( \gamma \).
C. Age of Information

To measure the freshness of status updates in IoT networks, the metric AoI is defined as the time elapsed since the generation of the latest status update that has been successfully decoded at the remote server. Note that, the AoI increases linearly with time if there is no status update decoded successfully at the remote server. An evolution of the AoI under study is illustrated in Fig. 3, where \( t^t_i \) and \( t^d_i \) denote the generation time at the IoT device and the arrival time at the remote server, respectively, pertaining to the \( i \)th successful status update.

More specifically, the average AoI is expressed as

\[
\bar{\Delta} = \lim_{t \to \infty} \frac{1}{t} \int_0^t \Delta(t) \, dt = \lim_{t \to \infty} \frac{1}{t} \sum_{i=1}^{N(t)} A_i
\]

where \( \Delta(t) \) is the instantaneous AoI, and \( N(t) \) is the number of status updates decoded successfully by the remote server at time \( t \). Further, \( \lambda = \lim_{t \to \infty} N(t)/t \) is defined as the rate of status updates decoded successfully at the remote server, and \( A_i \), marked by the shadow in Fig. 3, is the right trapezoidal area under the (waiting plus) delivery time of the \( i \)th status update. In addition, \( \mathbb{E}(A) \) denotes the expectation of \( A_i \), where the status update index \( i \) is omitted since \( A_i \), \( i = 1, 2, \ldots \), are independent and identically distributed (i.i.d.) random variables from the ergodic perspective.

In this work, we will investigate the AoI in finite block-length regime within HD-DF and FD-DF relaying networks based on the formulations of \( \lambda \) and \( \mathbb{E}(A) \).

D. Rayleigh Fading Channels

The majority of IoT infrastructures are deployed in rich scattering environments, for a wide range of applications in agriculture, industry, medicine, and allied sectors [1], [2]. In a non-line-of-sight scenario, such as a farm full of crops, a heavily built-up urban area, or a crowded corridor, Rayleigh fading is the most applicable model for the radio-frequency signal propagation [41], where the channel coefficient from a transmitter to a receiver is well-modelled as a random variable following a circularly-symmetric complex Gaussian distribution and, hence, the magnitude of the channel coefficient is Rayleigh distributed [42].

Moreover, Rayleigh fading is the most popular model to facilitate the calculations in the analysis and optimisation of wireless systems and networks. Since the main purpose of this work is to investigate and compare the performance of HD-DF and FD-DF relaying IoT networks from the AoI perspective, the exploitation of Rayleigh fading model allows us to achieve analytic expressions for the evaluation and optimisation.

The cdf of a Rayleigh fading \( \xi \), i.e., the magnitude of a channel coefficient, is given by

\[
F_\xi(\xi) = 1 - \exp(-\xi^2/H), \quad \xi \geq 0,
\]

where \( H \) is the variance of the channel coefficient.

We remark that, the design principles and optimisation results obtained through the Rayleigh fading model in this work can be easily generalised into the scenarios modelled by Rician fading or Nakagami fading, if the signal propagation is dominated by a line-of-sight component in special applications or services.

III. HALF-DUPLEX DECODE-AND-FORWARD RELAYING

In this section, the average AoI in the HD-DF relaying is formulated and minimised.

A. Average AoI

Within a HD-DF relaying IoT, the received SNRs at the relay and the remote server are given by

\[
\gamma_t = h_{st}p_s/\sigma^2
\]

and

\[
\gamma_d = h_{rd}p_r/\sigma^2,
\]

respectively, where \( h_{st} \) and \( h_{rd} \) denote the channel gains from the IoT device to the relay and from the relay to the remote server, respectively. Moreover, \( p_s \) is the IoT device’s transmit power, and \( p_r \) is the relay’s transmit power. The variance of additive white Gaussian noise (AWGN) is \( \sigma^2 \).

In a Rayleigh-fading channel, the magnitude of channel coefficient, \( \xi \in \{\sqrt{H_{st}}, \sqrt{H_{rd}}\} \), obeys the Rayleigh distribution. Substituting \( \xi_t^2 = \gamma_t/(p_s/\sigma^2) \) and \( \xi_d^2 = \gamma_d/(p_r/\sigma^2) \) into (7), we have the cdfs of \( \gamma_t \) and \( \gamma_d \) expressed as

\[
F_{\gamma_t}(x) = \begin{cases} 1 - \exp\left(-x/\bar{\gamma}_t\right), & x \geq 0, \\ 0, & x < 0 \end{cases}
\]

and

\[
F_{\gamma_d}(x) = \begin{cases} 1 - \exp\left(-x/\bar{\gamma}_d\right), & x \geq 0, \\ 0, & x < 0 \end{cases}
\]

respectively. Therefore, the received SNRs \( \gamma_t \) and \( \gamma_d \) follow the exponential distribution with means \( \bar{\gamma}_t = H_{st}p_s/\sigma^2 \) and \( \bar{\gamma}_d = H_{rd}p_r/\sigma^2 \), where \( H_{st} \) and \( H_{rd} \) are the variances of the channel coefficients.

Substituting (10) into (5), we obtain the relay’s average packet error probability as

\[
\bar{\varepsilon}_r = \beta r \int_{\alpha_r-1/(2\mu_r)}^{\alpha_r+1/(2\mu_r)} [1 - \exp(-x/\bar{\gamma}_r)] \, dx
\]
area pertaining to the \( i \)th status update, \( A_i \), can be written as
\[
A_i = \left[ (X_{i-1} + Y_{i-1} + X_i + Y_i)^2 - (X_{i-1} + Y_{i-1})^2 \right]/2
= (X_i^2 + Y_i^2)/2 + X_iY_i + (X_{i-1} + Y_{i-1})(X_i + Y_i),
\]
where \( X_i = K_{i,r}T_1 \) and \( Y_i = K_{i,d}T_2 \) are the time durations for the delivery of the \( i \)th status update in Phase 1 and Phase 2, respectively, with \( T_1 \) and \( T_2 \) denoting the time durations of a single transmission in Phase 1 and Phase 2, respectively. Then, we have
\[
\mathbb{E}(A) = \left[ \mathbb{E}(K_i^2) + 2\mathbb{E}^2(K_i) \right] T_1^2/2 + \left[ \mathbb{E}(K_d^2) + 2\mathbb{E}^2(K_d) \right] T_2^2/2
+ 3\mathbb{E}(K_d)T_1\mathbb{E}(K_d)T_2
= \frac{3}{2} \left( \frac{T_1}{1 - \bar{\epsilon}_r} + \frac{T_2}{1 - \bar{\epsilon}_d} \right)^2 + \frac{\bar{\epsilon}_rT_1^2}{2(1 - \bar{\epsilon}_r)^2} + \frac{\bar{\epsilon}_dT_2^2}{2(1 - \bar{\epsilon}_d)^2}.
\]

Furthermore, the rate of status updates decoded successfully at the remote server, \( \lambda \), is achieved at
\[
\lambda = \frac{1}{\mathbb{E}(K_i)T_1 + \mathbb{E}(K_d)T_2} = \left( \frac{T_1}{1 - \bar{\epsilon}_r} + \frac{T_2}{1 - \bar{\epsilon}_d} \right)^{-1}.
\]
Substituting (19) and (20) into (6), we obtain the average AoI of HD-DF relaying networks as
\[
\bar{\Delta}_{\text{HD}} = \frac{3}{2} \left( \frac{T_1}{1 - \bar{\epsilon}_r} + \frac{T_2}{1 - \bar{\epsilon}_d} \right) + \frac{\bar{\epsilon}_rT_1^2}{2(1 - \bar{\epsilon}_r)^2} + \frac{\bar{\epsilon}_dT_2^2}{2(1 - \bar{\epsilon}_d)^2}
= \frac{6 + \bar{\epsilon}_rT_1}{4(1 - \bar{\epsilon}_r)^2} + \frac{6 + \bar{\epsilon}_dT_2}{4(1 - \bar{\epsilon}_d)^2} \approx \bar{\Delta}_{\text{HD}},
\]
where the approximation (22) is obtained by assuming that the average transmission time of a packet in Phase 1 and that in Phase 2 are almost the same, i.e., \( T_1/(1 - \bar{\epsilon}_r) \approx T_2/(1 - \bar{\epsilon}_d) \). It agrees with the reality of packet transmissions.

In Fig. 5, the expression given by (21) is compared with the Monte-Carlo simulation results of the average AoI in HD-DF relaying over \( 10^6 \) status updates successfully decoded at the remote server, where \( D = 200 \) information bits are conveyed through the blocklengths \( n_1 = n_2 = 200 \) channel uses with the network bandwidth \( B = 1 \) MHz. The average channel gains \( H_r = -85 \) dB and \( H_d = -95 \) dB. The AWGN variance is \( \sigma^2 = -90 \) dBm. As shown in this figure, our derived average AoI expression (21) perfectly agrees with the simulation results. In the following, the average AoI of the HD-DF relaying will be minimised by optimising the blocklengths \( n_1 \) and \( n_2 \), on the basis of the expression (21).

B. Average AoI Minimisation

As shown in (12) and (13), higher received SNR results in lower packet error probability, thereby decreasing the average AoI. Hence, both the IoT device and the relay in the HD-DF relaying are encouraged to transmit signals at their maximum power, for the purpose of average AoI minimisation.
In the finite blocklength regime, larger blocklength leads to lower packet error probability but results in longer time duration for the transmission. Accordingly, given the transmit power at the IoT device and the relay, the average AoI of HD-DF relaying networks is minimised through the optimisation of the blocklengths \( n_1 \) and \( n_2 \).

As it is tough to minimise the average AoI using the expression in (21), we will minimise its approximation given by (23). Further, the time durations of a single transmission can be expressed as \( T_1 = n_1/B \) and \( T_2 = n_2/B \), where \( B \) is the bandwidth. Thus, the minimisation of average AoI is formulated by an optimisation problem as

\[ \mathcal{P}_1 : \min_{n_1, n_2} \frac{6 + \bar{\epsilon}_t}{4(1 - \bar{\epsilon}_t)} \frac{n_1}{B} + \frac{6 + \bar{\epsilon}_d}{4(1 - \bar{\epsilon}_d)} \frac{n_2}{B} \tag{24} \]

s.t. \( n_1 \geq n_{\text{min}}, \; n_1 \in \mathbb{Z}, \tag{24a} \)
\( n_2 \geq n_{\text{min}}, \; n_2 \in \mathbb{Z}, \tag{24b} \)

where \( n_{\text{min}} \) is the predetermined minimum blocklength.

Referring to (12) and (13), we may find that the first item in (24) is only related to \( n_1 \) and that the second item in (24) is only related to \( n_2 \). Therefore, \( \mathcal{P}_1 \) can be decoupled into two independent optimisation subproblems whose objective functions are the first and second items in (24). We will solve them one by one.

Before stepping further into the optimisation of the first item in (24) subject to \( n_1 \), we present an approximation of the relay’s average packet error probability, which has been validated in [30]. Based on (12), we have

\[ \bar{\epsilon}_t = 1 - \beta_t \bar{\gamma}_t \exp \left( -\frac{\alpha_r + 1/(2\beta_t)}{\bar{\gamma}_t} \right) \exp \left( \frac{1}{\beta_t \bar{\gamma}_t} \right) - 1 \]
\[ \approx 1 - \exp \left( -\frac{\alpha_r + 1/(2\beta_t)}{\bar{\gamma}_t} \right) \]
\[ \approx 1 - \exp \left( -\frac{2D/n_1 - 1 + \sqrt{\pi D \ln 2/n_1}}{\bar{\gamma}_t} \right), \tag{25} \]

where (25) and (26) are both achieved through the Taylor approximation of degree 1. Note that, (25) holds for a moderate SNR \( \bar{\gamma}_t \), and (26) holds for a relatively small coding rate \( D/n_1 \).

The optimisation subproblem of the first item in (24) is formulated as

\[ \mathcal{P}_2 : \min_{n_1} O_1(n_1) \tag{27} \]
\[ \text{s.t.} \; n_1 \geq n_{\text{min}}, \; n_1 \in \mathbb{Z}, \tag{27a} \]

where the objective function \( O_1(n_1) \) is given by

\[ O_1(n_1) = \frac{7n_1}{4B} \exp \left( \frac{2n_1^2 - 1 + \sqrt{\pi D \ln 2/n_1}}{\bar{\gamma}_t} \right) - \frac{n_1}{4B} \tag{28} \]

Relaxing the constraint \( n_1 \in \mathbb{Z} \) and allowing \( n_1 \) to take real values, i.e., \( n_1 \in \mathbb{R} \), we have the following lemma.

**Lemma 1.** The function \( O_1(n_1) \) is convex with respect to \( n_1 \).

**Proof:** The first-order derivative and second-order derivative of \( O_1(n_1) \) are given by

\[ O'_1(n_1) = \frac{7}{4B(1 - \bar{\epsilon}_t)} \left( 1 - \frac{2n_1^2 D \ln 2 + \sqrt{\pi D \ln 2}}{\bar{\gamma}_t n_1} \right) - \frac{1}{4B} \tag{29} \]

and

\[ O''_1(n_1) = \frac{7(D \ln 2)^2}{4B(1 - \bar{\epsilon}_t) \bar{\gamma}_t n_1^2} \left( \frac{2n_1^2}{\bar{\gamma}_t^2} + \frac{2n_1 + \sqrt{\pi D \ln 2}}{\bar{\gamma}_t^2} \right) > 0. \tag{30} \]

Therefore, the function \( O_1(n_1) \) is convex with respect to \( n_1 \), which completes the proof.

According to Lemma 1, the optimal blocklength \( n_1^* \) can be obtained by solving the Karush-Kuhn-Tucker (KKT) conditions. The Lagrangian is formulated as

\[ \mathcal{L}(O_1(n_1), \mu) = O_1(n_1) - \mu(n_1 - n_{\text{min}}), \tag{31} \]

where \( \mu \) is the Lagrange multiplier. Then, the KKT conditions are given by

\[ \frac{\partial \mathcal{L}(O_1(n_1), \mu)}{\partial n_1} = O'_1(n_1) - \mu = 0, \tag{32} \]
\[ \mu(n_1 - n_{\text{min}}) = 0, \tag{33} \]
\[ n_1 - n_{\text{min}} \geq 0, \tag{34} \]
\[ \mu \geq 0. \tag{35} \]

Concerning the constraint \( n_1 \in \mathbb{Z} \), the optimal blocklength \( n_1^* \) is obtained by

\[ n_1^* = \begin{cases} n_{\text{min}}, & O'_1(n_{\text{min}}) > 0, \\ \arg \min_{n_1 \in \{n_1^*, \ldots, n_1^\dagger\}} O'_1(n_1), & O'_1(n_{\text{min}}) \leq 0, \end{cases} \tag{36} \]

where \( n_1^* \) satisfies

\[ O'_1(n_1^*) = 0, \tag{37} \]

and can be obtained by the binary search algorithm.

Through the derivations similar with (26)–(36), we can obtain the optimal blocklength \( n_2^* \) as

\[ n_2^* = \begin{cases} n_{\text{min}}, & O'_2(n_{\text{min}}) > 0, \\ \arg \min_{n_2 \in \{n_2^*, \ldots, n_2^\dagger\}} O'_2(n_2), & O'_2(n_{\text{min}}) \leq 0, \end{cases} \tag{38} \]
where the function $O_2(n_2)$ and its first-order derivative $O_2'(n_2)$ are given by

$$O_2(n_2) = \frac{7n_2}{4B} \exp \left( \frac{2n_2}{\tilde{\gamma}_d} - 1 + \frac{\sqrt{\pi D} \ln n_2}{\tilde{\gamma}_d} \right) - \frac{n_2}{4B}$$  \hspace{1cm} (39)$$

and

$$O_2'(n_2) = \frac{7}{4B(1 - \tilde{\gamma}_d)} \left( 1 - \frac{2n_2}{\tilde{\gamma}_d} D \ln 2 + \sqrt{\pi D} \ln 2 \right) - \frac{1}{4B}. \hspace{1cm} (40)$$

respectively. Moreover, $n_2^*$ is the root of $O_2'(n_2) = 0$, which can be obtained by the binary search algorithm.

IV. FULL-DUPLEX DECODE-AND-FORWARD RELAYING

In this section, the average AoI in the FD-DF relaying is formulated and minimised.

A. Average AoI

In a FD-DF relaying IoT, the relay works in the FD mode and exploits self-interference (SI) cancellation techniques to mitigate the SI influence [43]–[45]. In this work, we consider the practical scenario with residual SI [46], [47]. Further, the blocklength in the link between the IoT device and the relay is assumed to be the same as that in the link between the relay and the remote server. Both are equal to $n \in \mathbb{Z}$.

When the relay receives the status update transmitted from the IoT device while forwarding its decoded status update to the remote server, its received signal, suffering from the SI, is expressed as

$$\gamma_t^\text{SI} = \sqrt{H_{sr}p_s e_s x_s + H_{sr}p_r e_r x_r + \omega_1}, \hspace{1cm} (41)$$

where $H_{sr}$ denotes the average channel gain in the link between the IoT device and the relay, and $H_{rt}$ denotes the average channel gain of the relay’s residual SI. Besides, $e_s$ and $e_r$ are both complex Gaussian variables with zero mean and unit variance. The signals transmitted from the IoT device and the relay are $x_s$ and $x_r$, respectively, and the AWGN is $\omega_1 \sim \mathcal{CN}(0, \sigma^2)$.

In the case that the successful decoding at the remote server is completed earlier than that at the relay, the relay’s received signal is free from the SI and obtained by

$$\gamma_t^\text{fSI} = \sqrt{H_{sr}p_s e_s x_s + \omega_2}, \hspace{1cm} (42)$$

where $\omega_2 \sim \mathcal{CN}(0, \sigma^2)$ is the AWGN.

The relay’s received SNR in these two cases are given by

$$\gamma_t = \frac{H_{sr}E_s e_s p_s + \sigma^2}{H_{sr}E_r p_r + \sigma^2}$$  \hspace{1cm} (43)$$

and

$$\gamma_t^\text{fSI} = \frac{H_{sr}E_s e_s p_s}{\sigma^2}, \hspace{1cm} (44)$$

where $E_s$ and $E_r$ are both exponentially distributed random variables with unit mean.

The cdf of $\gamma_t^\text{SI}$ is obtained in [48] as

$$F_{\gamma_t^\text{SI}}(x) = \begin{cases} 1 - \frac{1}{1 + (\tilde{\gamma}_t/\tilde{\gamma}_s)x} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right), & x \geq 0, \\ 0, & x < 0, \end{cases} \hspace{1cm} (45)$$

where $\tilde{\gamma}_s = H_{sr}p_s/\sigma^2$ and $\tilde{\gamma}_r = H_{sr}p_r/\sigma^2$.

Substituting (45) into (5), we obtain the average packet error probability in the presence of residual SI as

$$\hat{e}_r = \beta \frac{\alpha + 1/(2\beta)}{\tilde{\gamma}_s} \exp \left( -\frac{\gamma_r}{\tilde{\gamma}_s} \right) \left[ 1 - \frac{1}{1 + (\tilde{\gamma}_r/\tilde{\gamma}_s)x} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right) \right] dx \hspace{1cm} (46)$$

Referring to (12), the average packet error probability in the case of no SI at the relay can be obtained by

$$\hat{e}_r = 1 - \beta \frac{\alpha - 1/(2\beta)}{\tilde{\gamma}_s} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right) \left[ 1 - \frac{1}{1 + (\tilde{\gamma}_r/\tilde{\gamma}_s)x} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right) \right] dx \hspace{1cm} (47)$$

As there is no direct link between the IoT device and the remote server, the remote server’s average packet error probability is achieved at

$$\hat{e}_r = 1 - \beta \frac{\alpha - 1/(2\beta)}{\tilde{\gamma}_s} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right) \left[ 1 - \frac{1}{1 + (\tilde{\gamma}_r/\tilde{\gamma}_s)x} \exp \left( -\frac{x}{\tilde{\gamma}_s} \right) \right] dx \hspace{1cm} (48)$$

respectively.

Proof: See Appendix A.

As shown in Fig. 6, the shadow area pertaining to the $i$th status update, $A_i$, is calculated using

$$A_i = (X_{i-1} + M_i + Y_i)^2/2 - (X_{i-1} + Y_{i-1})^2/2, \hspace{1cm} (51)$$

where $X_i = K_{r,t}T_{FD}$ and $Y_i = E(K_{d,t}|K_{d,t} \leq K_{r,t}) T_{FD}$, with $T_{FD} = n/B$ and $K_{d,t}$ denoting the number of total (re)transmissions for the successful delivery of a single status update, without preemption, to the remote server. The random variable $M_i$ is the time gap between two consecutive status updates decoded successfully at the relay.

Lemma 3. The mean and the second moment of $M$ are
respectively, where \( \eta \) denotes the probability that the relay’s currently decoded status update is preempted by the succeeding one.

Proof: See Appendix B.

According to (51), the expectation of \( A_i \) is calculated using
\[
\mathbb{E}(A) = \mathbb{E}(M^2)/2 + \mathbb{E}(M)\mathbb{E}(K_i|K_i < K_d) + \mathbb{E}(M)\mathbb{E}(K_d|K_d \leq K_i)T_{FD}.
\]

Further, the rate of status updates decoded successfully at the remote server, \( \lambda \), is written as \( \lambda = 1/\mathbb{E}(M) \).

As a result, the average AoI in the FD-DF relaying is formulated as
\[
\bar{\Delta}_{FD} = \lambda \mathbb{E}(A) = \mathbb{E}(M^2)/2 + \mathbb{E}(K_i)T_{FD} + \mathbb{E}(K_d|K_d \leq K_i)T_{FD}
\]
\[
= \left[ \frac{\mathbb{E}(K_i^2)}{2\mathbb{E}(K_i)} \frac{\eta \mathbb{E}(K_i|K_i < K_d)}{1 - \eta} + \mathbb{E}(K_i) + \mathbb{E}(K_d|K_d \leq K_i) \right] T_{FD}.
\]

To obtain the analytic expression of \( \bar{\Delta}_{FD} \), we derive the probability \( \eta \) and the conditional expectations \( \mathbb{E}(K_i|K_i < K_d) \), \( \mathbb{E}(K_d|K_d \leq K_i) \) as
\[
\eta = \Pr(K_i < K_d) = \sum_{k=2}^{\infty} \Pr(K_d = k) \sum_{k'=1}^{k-1} \Pr(K_i = k') = \frac{1}{1 - \bar{\Delta}_{FD}} - \bar{\Delta}^*_{FD}.
\]

Substituting (49), (50), (55), (56), (57) into (54) and applying necessary arithmetic operations, we formulate the average AoI in the FD-DF relaying as
\[
\bar{\Delta}_{FD} = \left( \frac{2}{1 - \bar{\Delta}_{FD}} \frac{2}{1} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{2} \right) \frac{n}{B}
\]
\[
= \left( \frac{2}{1 - \bar{\Delta}_{FD}} \frac{2}{1} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{2} \right) \frac{n}{B}
\]
\[
= \frac{2}{1 - \bar{\Delta}_{FD}} \frac{2}{1} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{1 - \bar{\Delta}_{FD}} \frac{1}{2} \frac{n}{B}
\]

In Fig. 7, the expression (58) is plotted and compared with the Monte-Carlo simulation results of the average AoI in FD-DF relaying over 10^6 status updates successfully decoded at the remote server, where each status update contains \( D = 200 \) information bits, conveyed through the blocklength \( n = 200 \) channel uses with the network bandwidth \( B = 1 \) MHz. The average channel gains \( H_{df} = -85 \) dB and \( H_{dd} = -95 \) dB. The AWGN variance is \( \sigma^2 = -90 \) dBm. The average channel gain of the relay’s residual SI \( H_{rr} = -115 \) dB. As shown in this figure, our derived average AoI expression perfectly agrees with the simulation results. In the following, the average AoI of the FD-DF relaying will be minimised by optimising the relay’s transmit power \( p_t \) and the blocklength \( n \), on the basis of the expression (58).

### B. Average AoI Minimisation

To minimise the average AoI in the FD-DF relaying, the IoT device is encouraged to transmit signals at its maximum power, while the relay’s transmit power needs to be optimised. Apparently, higher transmit power at the relay leads to lower packet error probability at the remote server and, however, higher packet error probability at itself due to the SI.

The complicated expression of average AoI \( \bar{\Delta}_{FD} \) in (58) impedes further optimisation of the relay’s transmit power and the blocklength. Thus, we will minimise the average AoI based on the approximation \( \bar{\Delta}_{FD} \) in (59). Given the transmit power at
the IoT device, the minimisation of average AoI in the FD-DF relaying is formulated by an optimisation problem as

$$\mathcal{P}_3 : \min \hat{\Delta}_{\text{FD}} \quad \text{s.t.} \quad n \geq n_{\text{min}}, \quad n \in \mathbb{Z} \quad 0 < p_r \leq p_r^{\text{max}},$$

where $p_r^{\text{max}}$ is the relay’s maximum transmit power.

Referring to the approximation (26), $\bar{\varepsilon}_t^{\text{SI}}$ in (47) and $\bar{\varepsilon}_d$ in (48) are approximated to

$$\bar{\varepsilon}_t^{\text{SI}} \approx 1 - \exp \left[ -\frac{b(n)}{\gamma_{sr}} \right]$$

and

$$\bar{\varepsilon}_d \approx 1 - \exp \left[ -\frac{b(n)}{\gamma_d} \right]$$

through the Taylor approximation of degree 1 as well, where $b(n) = 2^D/n - 1 + \sqrt{\pi D} \ln 2/n$ is used for the simplicity of expression.

Moreover, $\bar{\varepsilon}_t^{\text{SI}}$ is approximated as

$$\bar{\varepsilon}_t^{\text{SI}} = 1 - \beta \int_{\alpha-1/(2\beta)}^{\alpha+1/(2\beta)} \frac{1}{1 + (\gamma_{sr}/\gamma_{tr})x} \exp \left( -\frac{x}{\gamma_{sr}} \right) \, dx \approx 1 - \frac{1}{\gamma_{sr} + \gamma_{tr}b(n)} \exp \left( -\frac{b(n)}{\gamma_{sr}} \right)$$

where the approximation (63) is obtained by replacing the integrand with $e^{-(\alpha+1/(2\beta))}/\gamma_{sr} / (1 + (\gamma_{sr}/\gamma_{tr})[\alpha + 1/(2\beta)])$ due to the small interval length $1/\beta$ of the integration, and (64) is achieved through the Taylor approximation of degree 1.

Next, we adopt a low-complexity iterative algorithm to solve $\mathcal{P}_3$, i.e., two optimisation subproblems are characterised for the relay’s optimal transmit power given the blocklength and the optimal blocklength given the relay’s transmit power.

1) Optimal Transmit Power at the Relay: Given the blocklength $n$, the average packet error probabilities $\bar{\varepsilon}_t^{\text{SI}}, \bar{\varepsilon}_t^{\text{SI}}$ and $\bar{\varepsilon}_d$ are simplified as

$$\bar{\varepsilon}_t^{\text{SI}} = 1 - \frac{a}{1 + k\gamma_d},$$

$$\bar{\varepsilon}_t^{\text{SI}} = 1 - a,$$

$$\bar{\varepsilon}_d = 1 - \exp \left( -\frac{b}{\gamma_d} \right),$$

where $a = \exp \left[ -\left( \frac{2^D}{n} - 1 + \sqrt{\pi D} \ln 2/n \right) / \gamma_{sr} \right]$. $b = 2^D/n - 1 + \sqrt{\pi D} \ln 2/n$ and $k = bH_{tr}/(H_{rd}\gamma_d)$ are all constants. As the remote server’s average SNR $\gamma_d = H_{ad}p_r/\sigma_r^2$, the subproblem of the relay’s optimal transmit power is expressed as

$$\mathcal{P}_4 : \min \bar{O}_3(\gamma_d) \quad \text{s.t.} \quad (60b),$$

where the objective function $O_3(\gamma_d)$ is

$$O_3(\gamma_d) = \frac{\bar{\varepsilon}_t^{\text{SI}} - \bar{\varepsilon}_t^{\text{SI}}}{\bar{\varepsilon}_d} \left( \frac{1}{1 + \gamma_{sr}^{\gamma_{tr}} + 1 - \gamma_{sr}^{\gamma_{tr}}} + \frac{1}{\gamma_d} \right) - \frac{1}{\gamma_d} \exp \left( \frac{b}{\gamma_d} \right).$$

The first-order derivative of $O_3(\gamma_d)$ is given by

$$O'_3(\gamma_d) = G(\gamma_d) \frac{\exp b/\gamma_d}{\gamma_d} (1 + k\gamma_d)^2 (2 + 2k\gamma_d - a)^2,$$

where $G(\gamma_d)$ is defined as

$$G(\gamma_d) = \kappa_1\gamma_d^2 + \kappa_2\gamma_d^3 + \kappa_3\gamma_d^2 + \kappa_4\gamma_d + \kappa_5$$

with

$$\kappa_1 = (4 + 2a - 8b) \gamma_d^2 - 2abk \gamma_d - a^2 k^3,$$

$$\kappa_2 = (8 + 2abk \gamma_d + a^2 b \gamma_d - 28b k - 2a^2) k^2,$$

$$\kappa_3 = (4 + 14abk \gamma_d - 2a - 36bk) k,$$

$$\kappa_4 = (14ab - 20b - 2a^2 b) k,$$

$$\kappa_5 = -b(2 - a)^2.$$

As $\gamma_d^{-2}(1 + k\gamma_d)^{-2}(2 + 2k\gamma_d - a)^{-2} \exp b/\gamma_d > 0$, the monotonicity of the objective function $O_3(\gamma_d)$ can be derived from $G(\gamma_d)$. Moreover, we have $G(0) = -b(2 - a)^2 < 0$. Let $\mathcal{R}$ be the set containing all positive real roots of the equation $G(\gamma_d) = 0$, which can be obtained by the general formula for solving quartic equations. Consequently, the solution to $\mathcal{P}_4$ is

$$p_r^* = \begin{cases} p_r^{\text{max}}, & \text{if } \gamma_d \in \mathcal{R}, \gamma_d \leq H_{ad}p_r^{\text{max}}/\sigma_r^2 < \bar{\gamma}_d, \\ p_r^*, & \text{otherwise}, \end{cases}$$

where $\bar{\gamma}_d^{\text{min}}$ is the smallest element in the set $\mathcal{R}$ if $\mathcal{R} \neq \emptyset$, and $\bar{\gamma}_d^{\text{min}} < +\infty$ if $\mathcal{R} = \emptyset$. Meanwhile, $p_r^*$ is obtained by

$$p_r^* = \arg \min_{\gamma_d \in \mathcal{R}, \gamma_d \leq H_{ad}p_r^{\text{max}}/\sigma_r^2} G(\gamma_d).$$

2) Optimal Blocklength: Given the relay’s transmit power $p_r$, the average channel gains $\gamma_d$ and $\gamma_{tr}$ are fixed. As the average SNRs $\gamma_{sr}, \gamma_{tr}, \gamma_d$ are all constants, the subproblem of the optimal blocklength is formulated as

$$\mathcal{P}_5 : \min \bar{O}_4(n)$$
where the objective function \( O_4(n) \) can be written as
\[
O_4(n) = \frac{\frac{\varepsilon SI - \varepsilon^{SI}}{\varepsilon d}}{1 - \varepsilon d} \left( 1 + \frac{1}{1 + \varepsilon SI} \right) + \frac{1}{1 - \varepsilon SI} - \frac{\varepsilon^{SI}}{\varepsilon d} - \frac{1}{1 - \varepsilon d} \right) n 
+ \left( \frac{2 \rho b \exp(b/\gamma d) + \rho b \exp(b/\gamma d)}{2(1 + \rho b) + \rho b \exp(b/\gamma d) - 1} + 1 + \rho b \right) n 
+ \left( \frac{2 \exp(b/\gamma d) + \exp(b/\gamma d)}{2} \right) n
\]
with \( \rho = \gamma_r/\gamma_{sr} \) is used for the simplicity of expression.

Note that, the objective function \( O_4(n) \) is not necessarily convex with respect to the blocklength \( n \). To solve this subproblem effectively, we first derive an upper bound on \( n \). If the blocklength exceeds this upper bound, \( O_4(n) \) will increase monotonically. As such, the range of optimal blocklength is shortened. Then, we utilise an exhaustive algorithm to obtain the optimal blocklength \( n^* \).

To begin with, the first-order derivatives of \( \varepsilon_d, \varepsilon^{SI}_r \) and \( \varepsilon^{SI}_d \) are given by
\[
\varepsilon_d' = \frac{b'}{\gamma_d} (1 - \varepsilon_d), \quad \varepsilon^{SI}_r' = \frac{b'}{\gamma_{sr}} (1 - \varepsilon^{SI}_r), \quad \varepsilon^{SI}_d' = \frac{(1 + \rho b + \rho \gamma_{sr}) b'}{1 + \rho b} \gamma_{sr} (1 - \varepsilon^{SI}_d),
\]
where \( b'(n) = -(\ln 2)2^D/nD/n^2 - \sqrt{\pi D} \ln 2/n^2 < 0 \). Then, the first-order derivative of \( O_4(n) \) is given in (78), at the top of next page.

As \( nb'(n) = -(\ln 2)2^D/nD/n - \sqrt{\pi D} \ln 2/n \) is a monotonically increasing function of \( n \), the objective function \( O_4(n) \) increases monotonically when the blocklength \( n \) satisfies
\[
\begin{cases} 
3 + 4nb'(n)/\gamma_{sr} > 0, \\
1 + (4/\gamma_d + 2/\gamma_{sr} + 2\rho) nb'(n) > 0,
\end{cases}
\]
\[
n \geq n_{\min}, \quad n \in \mathbb{Z}.
\]

The minimum value of \( n \) satisfying inequalities (79) is denoted by \( n^* \) and can be obtained through the binary search algorithm, which shortens the range of the optimal blocklength to \([n_{\min}, n^*]\). Subsequently, an exhaustive search algorithm is ready to find the optimal blocklength \( n^* \). Our proposed iterative algorithm conceived for solving the minimisation problem \( \mathcal{P}3 \) is summarised in Algorithm 1.

### Algorithm 1

The iterative algorithm for solving \( \mathcal{P}3 \).

**Input:**
- Parameters: \( B, D, n_{\min}, p_s, p_r^{max}, H_{sr}, H_{rt}, H_{rd}, \sigma^2; \)
- An arbitrary small number \( \delta > 0 \);

**Output:**
- Optimal transmit power at the relay \( p_r^*; \)
- Optimal blocklength \( n^*; \)
1. Initialise the blocklength \( n = n_{\min}; \)
2. **repeat**
3. Updating \( p_r \) by solving (71);
4. Obtaining \( n^* \) by solving (79);
5. Updating n by an exhaustive search in \([n_{\min}, n^*] \);
6. **until** The difference in \( \tilde{\Delta}_{FD}(p_r, n) \) before and after updating is less than \( \delta \).
7. \( p_r^* = p_r, \quad n^* = n \).

V. NUMERICAL RESULTS

In this section, illustrative numerical results are provided to compare the AoI performance of HD-DF and FD-DF relaying IoT networks, where the default parameters are set as follows.

The network bandwidth is \( B = 1 \) MHz. For a status update, there are \( D = 200 \) information bits conveyed by the minimum blocklength \( n_{\min} = 100 \) channel uses. The AWGN variance is \( \sigma^2 = -90 \) dBm. The average channel gain between the IoT device and the relay is \( H_{sr} = -85 \) dB, whilst the average channel gain between the relay and the remote server is \( H_{rd} = -95 \) dB. In the HD-DF relaying IoT networks, the relay transmits its successfully decoded status updates at the maximum power \( p_r^{max} \) to minimise the average AoI.

To begin with, the average AoI in HD-DF relaying, \( \tilde{\Delta}_{HD} \) in (21), versus the blocklengths \( n_1 \) and \( n_2 \) in Phases 1 and 2, is plotted in Fig. 8, where the IoT device’s transmit power \( p_s = 5 \) dBm and the relay’s transmit power \( p_r = 15 \) dBm. The average AoI in FD-DF relaying, \( \Delta_{FD} \) in (58), versus the blocklength \( n \) and the relay’s transmit power \( p_r \), is plotted in Fig. 9, where \( p_s = 5 \) dBm and the average channel gain of the relay’s residual SI \( H_{sr} = -115 \) dB.

To illustrate the validity of the approximation \( \tilde{\Delta}_{HD} \approx \Delta_{FD} \) in (23) and ensuring optimisation of the blocklengths, we plot the minimised average AoI of HD-DF relaying, versus the IoT device’s transmit power \( p_s \), in Fig. 10, where the optimal blocklengths \( n_1^* \) and \( n_2^* \) are obtained by (36) and (38), respectively. For the sake of comparison, the optimal blocklengths \( n_1^* \) and \( n_2^* \) are obtained through exhaustive search upon (21). As shown in this figure, the minimised results of the expression \( \tilde{\Delta}_{HD}(n_1^*, n_2^*) \) in (21) are matched perfectly by those of its approximation \( \Delta_{HD}(n_1^*, n_2^*) \) in (23). Moreover, the minimised average AoI results obtained by our proposed optimisation, \( \Delta_{FD}(n_1^*, n_2^*) \) and \( \Delta_{HD}(n_1^*, n_2^*) \), perfectly agree with the optimal solution via exhaustive search \( \Delta_{HD}(n_1^*, n_2^*) \), which substantiates the credibility of our optimised blocklengths \( n_1^* \) and \( n_2^* \).

For the FD-DF relaying IoT networks, to validate the effectiveness of the approximation \( \Delta_{FD}(p_r, n) \) in (59) and the iterative algorithm given in Algorithm 1, we compare the minimised average AoI results obtained by our iterative algorithm, including \( \Delta_{FD}(p_r^*, n^*) \) in (58) and its approximation \( \Delta_{FD}(p_r^*, n^*) \) in (59), with the optimal result via an exhaustive search upon (58), \( \Delta_{FD}(p_r^*, n^*) \), in Fig. 11. These results are plotted versus the relay’s maximum transmit power \( p_r^{max} \), and the range \([0, p_r^{max}] \) is discretized for the search of \( p_r^* \). As shown in this figure, all the three results perfectly agree with each other, which confirms the validity of the approximation (59) and our iterative algorithm.

In Fig. 12, we compare the minimised average AoI of HD-DF relaying, \( \tilde{\Delta}_{HD}(n_1^*, n_2^*) \), with that of FD-DF relaying.
\( O'_d(n) = \frac{3 + \bar{\epsilon}_r^{\text{SI}} + 4n'b'/\bar{\gamma}_{st}}{2(1 - \bar{\epsilon}_r^{\text{SI}})} + \frac{1}{1 - \bar{\epsilon}_d} \left[ \frac{3 + \bar{\epsilon}_r^{\text{SI}}}{1 - \bar{\epsilon}_r^{\text{SI}}} + \frac{3n'b'}{\gamma_d} + \frac{n'b'(1 - \bar{\epsilon}_r^{\text{SI}})}{(1 + \bar{\epsilon}_r^{\text{SI}})} + \frac{nb'(1 + \rho b + \rho \bar{\gamma}_{st})}{(1 + \bar{\epsilon}_r^{\text{SI}})} + \frac{nb'(1 - \bar{\epsilon}_r^{\text{SI}})}{(1 + \bar{\epsilon}_r^{\text{SI}})} \right] \)

\[
= \frac{1 - \bar{\epsilon}_r^{\text{SI}}}{(1 - \bar{\epsilon}_r^{\text{SI}})(1 - \bar{\epsilon}_d)} \left[ -1 + \frac{n'b'(1 + \rho b + \rho \bar{\gamma}_{st})}{\bar{\gamma}_d(1 + \rho b)} - \frac{n'b'}{\bar{\gamma}_d} - \frac{n'b'}{\bar{\gamma}_{st}} \right] \frac{\rho b(1 - \bar{\epsilon}_r^{\text{SI}})^2}{(1 - \bar{\epsilon}_d)(1 + \bar{\epsilon}_r^{\text{SI}})^2} \frac{nb'}{\bar{\gamma}_d} + \frac{nb'(1 + \rho b + \rho \bar{\gamma}_{st})}{(1 + \rho b)\bar{\gamma}_{st}} > 0
\]

\[ > \frac{3 + 4n'b'/\bar{\gamma}_{st}}{2(1 - \bar{\epsilon}_r^{\text{SI}})} + \frac{1}{1 - \bar{\epsilon}_d} \left[ 1 + \frac{4n'b'}{\bar{\gamma}_d} + \frac{2n'b'}{\bar{\gamma}_{st}} (1 + \rho \bar{\gamma}_{st}) \right]. \tag{78} \]

Fig. 8. The average AoI of the HD-DF relaying IoT, \( \hat{\text{AoI}}_{\text{HD}} \) in (21), versus the packet blocklengths \( n_1 \) and \( n_2 \) in Phases 1 and 2, with \( p_s = 5 \) dBm and \( p_r = 15 \) dBm.

Fig. 9. The average AoI of the FD-DF relaying IoT, \( \hat{\text{AoI}}_{\text{FD}} \) in (34), versus the packet blocklength \( n \) and the relay’s transmit power \( p_r \), with \( p_s = 5 \) dBm and \( H_{tr} = -115 \) dB.

The \( \hat{\text{AoI}}_{\text{FD}}(p_r', n') \), which are both reduced as the IoT device’s transmit power \( p_s \) increases. In the HD-DF relaying, the average packet error probability \( \bar{\epsilon}_r \) decreases upon increasing \( p_s \) and, consequently, the number of total (re)transmissions from the IoT device to the relay is reduced, which shortens the time for the delivery of status updates. In the FD-DF relaying, the increase of \( p_s \) causes a decrease of average packet error probabilities \( \bar{\epsilon}_r^{\text{SI}} \) and \( \bar{\epsilon}_r^{\text{SI}} \), which is ultimately reflected by the decrease of average AoI. As shown in the minimised average AoI comparisons between the HD-DF and the FD-DF relaying, the average AoI of FD-DF relaying is smaller than that of HD-DF relaying when \( p_s \) is above a threshold value, given the relay’s SI cancellation capability which pertains to the value of \( H_{tr} \). Moreover, the threshold for \( p_s \) is lowered upon enhancing the relay’s SI cancellation capability, which provides an instructive suggestion on how to select a relaying scheme based on the IoT device’s transmit power and the relay’s SI cancellation capability.

A special case in Fig. 12 is the result \( \hat{\text{AoI}}_{\text{FD}}(p_r', n') \) with \( H_{tr} = -90 \) dB, which exhibits a two-stage decrease: a first quick fall followed by a slowing down. The main reason behind this is that the relay’s SI cancellation capability is not strong enough to leave the error probability \( \bar{\epsilon}_r^{\text{SI}} \) dominated by the IoT device’s transmit power \( p_s \). The first quick fall is prominently contributed by the error probability \( \bar{\epsilon}_r^{\text{SI}} \) whose slope is large in the region of low transmit power \( p_s \). The second stage is caused by the joint contribution of \( \bar{\epsilon}_r^{\text{SI}} \) and \( \bar{\epsilon}_r^{\text{SI}} \) whose slopes both decrease as \( p_s \) increases.

In addition, the impact of the relay’s maximum transmit power \( p_r'_{\text{max}} \) on the minimised average AoI in both HD-DF and FD-DF relaying IoT networks is investigated in Fig. 13, where the minimised average AoI of either HD-DF or FD-DF is decreased to a certain level as \( p_r'_{\text{max}} \) increases. As implied by its convergence property, the minimised average AoI will not be influenced by \( p_r'_{\text{max}} \) if the latter is sufficiently high. Moreover, similar with the observation in Fig. 12, the stronger
is the relay’s SI cancellation capability, the smaller is the minimised average AoI of the FD-DF relaying. Further, given $p_{t_{r}}^{\text{max}}$, the FD-DF relaying outperforms the HD-DF relaying when the relay’s SI cancellation capability is above certain threshold. Note that, when $p_{t_{r}}^{\text{max}}$ is large enough, the relay’s SI cancellation capability preserves its dominant position in the minimised average AoI of FD-DF relaying, which is owing to the damage caused by SI in the relay’s decoding of its received status packets from the IoT device.

VI. CONCLUSIONS

To achieve timely status updates in IoT monitoring networks, short-packet relaying has been investigated in this paper, where the status updates generated at an IoT device are delivered to a remote server with the aid of a relay in both HD-DF and FD-DF modes. For quantifying the data freshness of status updates, we formulated the average AoI for both relaying modes in finite blocklength regime. For the HD-DF relaying, the optimisation problem was established to minimise the average AoI with optimal blocklengths for the delivery of a status update in Phases 1 and 2, which was solved through a perfect approximation of the average AoI. For the HD-DF relaying, the optimisation problem was built on the basis of the average AoI minimisation through optimal designs of the blocklength and the relay’s transmit power, which was solved by our proposed iterative algorithm. Illustrative numerical results substantiated the validity of our theoretical formulations and the feasibility of our proposed algorithms. Moreover, the minimised average AoI comparisons between HD-DF and FD-DF relaying IoT networks have shown that the latter outperforms the former if the relay has a strong SI cancellation capability. In other words, the utilisation of FD mode will help with the improvement of data freshness in the IoT networks, as long as sufficient SI has been cancelled.

APPENDIX A

PROOF OF LEMMA 2

According to the law of total probability, the probability of $K = k$ is given in (80), where $K$ denotes the number of total
\[
\Pr(K_r = k) = \sum_{k'=1}^{k-1} \Pr(K_r = k | K_d = k') \Pr(K_d = k') + \sum_{k'=k}^{\infty} \Pr(K_r = k | K_d = k') \Pr(K_d = k')
\]
\[
= \sum_{k'=1}^{k-1} \bar{\varepsilon}_d^{k-1}(1 - \bar{\varepsilon}_d)(\bar{\varepsilon}_d^{SI})^{k-1} - \bar{\varepsilon}_d^{SI} + \sum_{k'=k}^{\infty} \bar{\varepsilon}_d^{k-1}(1 - \bar{\varepsilon}_d)(\bar{\varepsilon}_d^{SI})^{k-1} - 1 - \bar{\varepsilon}_d^{SI} + \frac{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}}{1 - \bar{\varepsilon}_d^{SI}} \frac{(k-1)(1 - \bar{\varepsilon}_d)(1 - \bar{\varepsilon}_d^{SI})(\bar{\varepsilon}_d^{SI})^{k-1} + (1 - \bar{\varepsilon}_d^{SI})(\bar{\varepsilon}_d^{SI})^{k-1}}{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}}.
\]
\[
= \frac{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}}{1 - \bar{\varepsilon}_d^{SI}} \frac{(1 - \bar{\varepsilon}_d)(1 - \bar{\varepsilon}_d^{SI})(\bar{\varepsilon}_d^{SI})^{k-1} + (1 - \bar{\varepsilon}_d^{SI})(\bar{\varepsilon}_d^{SI})^{k-1}}{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}},
\]
\[
\text{where } \bar{\varepsilon}_d^{SI} \neq \bar{\varepsilon}_d^{SI}. \text{ In the case that } \bar{\varepsilon}_d^{SI} = \bar{\varepsilon}_d^{SI}, \text{ (81) is recalculated as}
\]
\[
\mathbb{E}(K_r) = \frac{(1 - \bar{\varepsilon}_d)(1 - \bar{\varepsilon}_d^{SI})}{\bar{\varepsilon}_d} \sum_{k=1}^{\infty} k(1 - k)(\bar{\varepsilon}_d^{SI})^{k-1} + (1 - \bar{\varepsilon}_d^{SI}) \sum_{k=1}^{\infty} k \left( \bar{\varepsilon}_d^{SI} \right)^{k-1} = \frac{1 + \bar{\varepsilon}_d^{SI} - 2\bar{\varepsilon}_d^{SI}}{1 - \bar{\varepsilon}_d^{SI}}.
\]
\[
\text{We remark that, (81) and (82) are equivalent to the same expression. As a general result, the mean of } K_r \text{ is expressed as (49) in Lemma 2.}
\]
\[
\mathbb{E}(K_r^2) = \sum_{k=1}^{\infty} k^2 \Pr(K_r = k)
\]
\[
= \frac{\bar{\varepsilon}_d^{SI}(1 - \bar{\varepsilon}_d)(1 - \bar{\varepsilon}_d^{SI})}{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}} \sum_{k=1}^{\infty} k^2 (\bar{\varepsilon}_d^{SI})^{k-1} + \frac{(\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI})(1 - \bar{\varepsilon}_d^{SI})}{\bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}} \sum_{k=1}^{\infty} k \left( \bar{\varepsilon}_d^{SI} \right)^{k-1}
\]
\[
= \frac{1 + \bar{\varepsilon}_d^{SI} - 2\bar{\varepsilon}_d^{SI}}{(1 - \bar{\varepsilon}_d^{SI})^2} + \frac{2}{1 - \bar{\varepsilon}_d^{SI} + 1 - \bar{\varepsilon}_d^{SI}} - \left( \frac{2}{1 - \bar{\varepsilon}_d^{SI} - \bar{\varepsilon}_d^{SI}} \right) \frac{2}{1 - \bar{\varepsilon}_d^{SI} + 1 - \bar{\varepsilon}_d^{SI} - 1}
\]
\[
\text{where } \bar{\varepsilon}_d^{SI} \neq \bar{\varepsilon}_d^{SI}. \text{ In the case that } \bar{\varepsilon}_d^{SI} = \bar{\varepsilon}_d^{SI}, \text{ (83) is recalculated as}
\]
\[
\mathbb{E}(K_r^2) = \frac{(1 - \bar{\varepsilon}_d)(1 - \bar{\varepsilon}_d^{SI})}{\bar{\varepsilon}_d} \sum_{k=1}^{\infty} k^2(1 - k)(\bar{\varepsilon}_d^{SI})^{k-1} + (1 - \bar{\varepsilon}_d^{SI}) \sum_{k=1}^{\infty} k^2 \left( \bar{\varepsilon}_d^{SI} \right)^{k-1}
\]
\[
= \frac{3 + \bar{\varepsilon}_d^{SI}(1 + \bar{\varepsilon}_d^{SI} - 2\bar{\varepsilon}_d^{SI})}{(1 - \bar{\varepsilon}_d^{SI})^3} - \frac{2}{(1 - \bar{\varepsilon}_d^{SI})^2}.
\]
\[
\text{As (83) and (84) are equivalent to the same expression, the second moment of } K_r \text{ is expressed as (50) in Lemma 2.}
\]

**APPENDIX B**

**PROOF OF LEMMA 3**

The mean of } M \text{ is formulated as}
\[
\mathbb{E}(M) = \mathbb{E}(X | K_r \geq K_d) + \sum_{l=0}^{\infty} \eta^l (1 - \eta) \mathbb{E}(X | K_r < K_d)
\]
\[
= \mathbb{E}(X | K_r \geq K_d) + \frac{\eta}{1 - \eta} \mathbb{E}(X | K_r < K_d)
\]
\[
= \frac{\mathbb{E}(K_r) T_{FD}}{1 - \eta}.
\]
where (a) holds according to the law of total expectation, and \( \eta \) denotes the probability that the relay’s currently decoded status update is preempted by the succeeding one.

The second moment of } M \text{ is calculated using}
\[
\mathbb{E}(M^2) = \mathbb{E}(X^2 | K_r \geq K_d) + \sum_{l=0}^{\infty} \eta^l (1 - \eta) \mathbb{E}(X^2 | K_r < K_d)
\]
\[
+ \sum_{l=0}^{\infty} \eta^l (1 - \eta) \mathbb{E}(X | K_r \geq K_d) \mathbb{E}(X | K_r < K_d) + \frac{2\eta}{1 - \eta} \mathbb{E}(X | K_r \geq K_d) \mathbb{E}(X | K_r < K_d)
\]
\[
+ \frac{2\eta^2}{(1 - \eta)^2} \mathbb{E}(X | K_r < K_d)
\]
\[
= \mathbb{E}(X^2) + \frac{2\eta \mathbb{E}(X) \mathbb{E}(X | K_r < K_d)}{1 - \eta} + \frac{2\eta^2}{(1 - \eta)^2}
\]
\[
= \left[ \mathbb{E}(K_r^2) + 2\eta \mathbb{E}(K_r) \mathbb{E}(K_r | K_r < K_d) \right] T_{FD}^2.
\]

**REFERENCES**

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